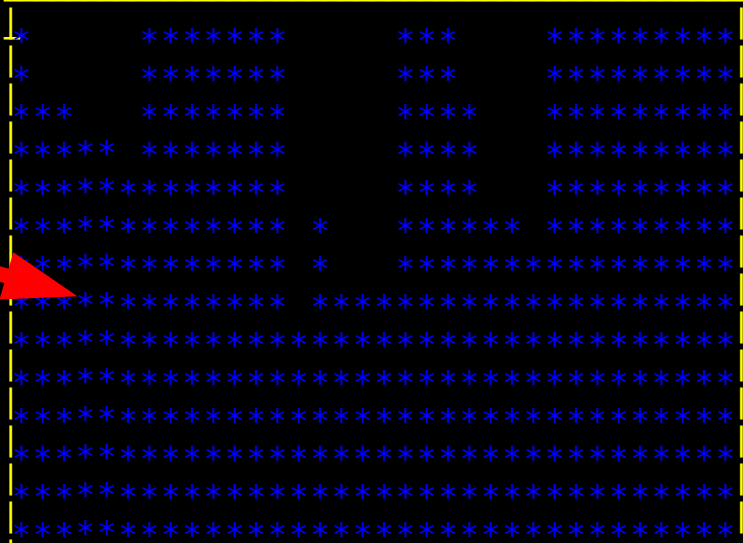


Láser



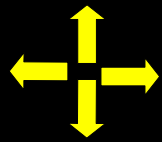
Posición
x = 1.454
y = 0.321
rot = 0.675

Velocidad
trans = 0.1
ang = 0.2

Odometría

Comandos

Movimiento



q: + vtrans w: + vrot
a: - vtrans s: - vrot

esc: terminar